

Information flow control revisited:

**Noninfluence =
Noninterference + Nonleakage**

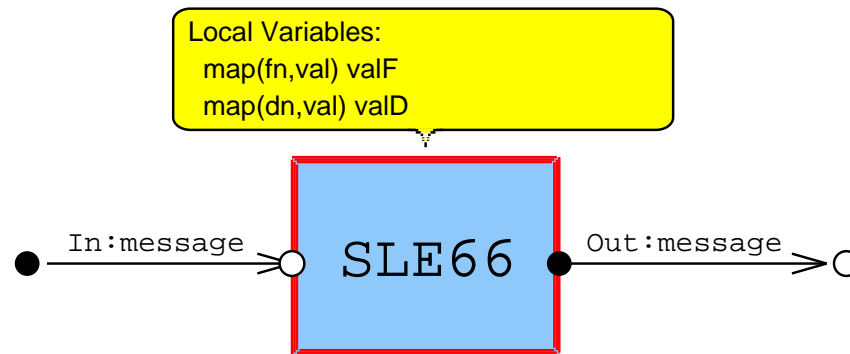
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Motivation

Task: Security analysis for Infineon SLE66 smart card processor



Main concern: confidentiality of on-chip secrets

Initial solution: secret values do not appear as output

Problem: leakage of re-encoded and partial information

Maximal solution: observable output *independent* of secrets

Approach: some sort of noninterference

Overview

- noninterference
 - classical notion
 - unwinding
 - nondeterminism
 - improvements
- nonleakage
 - motivation, notion, variants
 - application
- noninfluence
- insights

Generic notions

System model: — Moore automaton

$step : action \times state \rightarrow state$

$run : action^* \times state \rightarrow state$

— also **nondeterministic** variants

Security model:

$domain$ — secrecy level/area

$obs : domain \times state \rightarrow output$

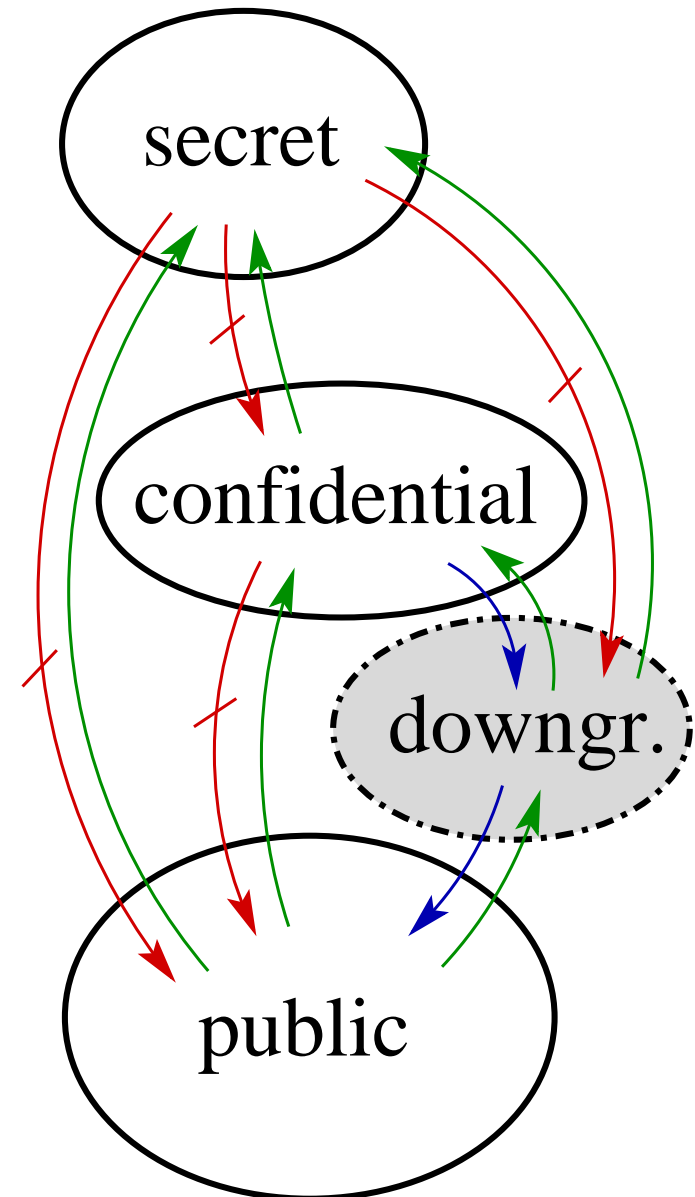
$dom : action \rightarrow domain$ — input domain

Policy or interference relation

$\rightsquigarrow : \wp(domain \times domain)$

— always reflexive, possibly **intransitive**

Noninterference relation: $\not\rightsquigarrow$



Noninterference [GM82/84,Rus92]

Aim: secrecy of the presence/absence of actions

$$\text{noninterference} \equiv \forall \alpha u. \text{obs}(u, \text{run}(\alpha, s_0)) = \text{obs}(u, \text{run}(\text{ipurge}(u, \alpha), s_0))$$

$\text{ipurge}(u, \alpha)$ = "remove from the sequence α all actions that may not influence u , directly or via the domains of subsequent actions within α "

Observational equivalence/relation

$$\cdot \triangleleft \cdot \stackrel{\cdot}{\simeq} \cdot \triangleleft \cdot : \text{domain} \rightarrow \wp(\text{state} \times \text{action}^* \times \text{state} \times \text{action}^*)$$

$$s \triangleleft \alpha \stackrel{u}{\simeq} t \triangleleft \beta \equiv \text{obs}(u, \text{run}(\alpha, s)) = \text{obs}(u, \text{run}(\beta, t))$$

$$\text{noninterference} \equiv \forall \alpha u. s_0 \triangleleft \alpha \stackrel{u}{\simeq} s_0 \triangleleft \text{ipurge}(u, \alpha)$$

ipurge & sources

ipurge : $domain \times action^* \rightarrow action^*$

$ipurge(u, []) = []$

$ipurge(u, a \frown \alpha) =$ if $dom(a) \in sources(a \frown \alpha, u)$
then $a \frown ipurge(u, \alpha)$ else $ipurge(u, \alpha)$

sources(α, u) = “all domains of actions in α that may influence u , directly or via the domains of subsequent actions within α ”

e.g., $v \in sources(a_1 \frown a_2 \frown a_3 \frown a_4, u)$

if $v = dom(a_2) \rightsquigarrow dom(a_4) \rightsquigarrow u$ (even if $v \not\rightsquigarrow u$)

sources : $action^* \times domain \rightarrow \wp(domain)$

$sources([], u) = \{u\}$

$sources(a \frown \alpha, u) = sources(\alpha, u) \cup$
 $\{w. \exists v. dom(a) = w \wedge w \rightsquigarrow v \wedge v \in sources(\alpha, u)\}$

Unwinding

Problem: noninterference is global property, to be shown for any α

Idea: induction on α shows preservation of

unwinding relation $\sim : domain \rightarrow \wp(state \times state)$

— some kind of equality on the sub-state belonging to the domain

— **no need** to be reflexive, symmetric, nor transitive [Man00/03]

— lifting to sets of domains: $s \overset{U}{\sim} t \equiv \forall u \in U. s \overset{u}{\sim} t$

Local properties: essentially $s \overset{u}{\sim} t \longrightarrow step(a, s) \overset{u}{\sim} step(a, t)$

(**step consistency, step respect, local respect**)

Proof sketch

Theorem Goal: $obs(u, run(\alpha, s_0)) = obs(u, run(ipurge(u, \alpha), s_0))$

Main Lemma: $\forall s t. s \stackrel{sources(\alpha, u)}{\approx} t \longrightarrow run(\alpha, s) \stackrel{u}{\approx} run(ipurge(u, \alpha), t)$

Proof of Theorem: specialize by $s = t = s_0$, use $s_0 \stackrel{sources(\alpha, u)}{\approx} s_0$,
and apply **output consistency** $\forall u s t. s \stackrel{u}{\approx} t \longrightarrow obs(u, s) = obs(u, t)$

Proof of Main Lemma: by induction $\alpha' \longrightarrow a \frown \alpha'$
 $s \stackrel{sources(a \frown \alpha', u)}{\approx} t$ implies

if $dom(a) \in sources(a \frown \alpha', u)$

(step consistency + respect): then $step(a, s) \stackrel{sources(\alpha', u)}{\approx} step(a, t)$

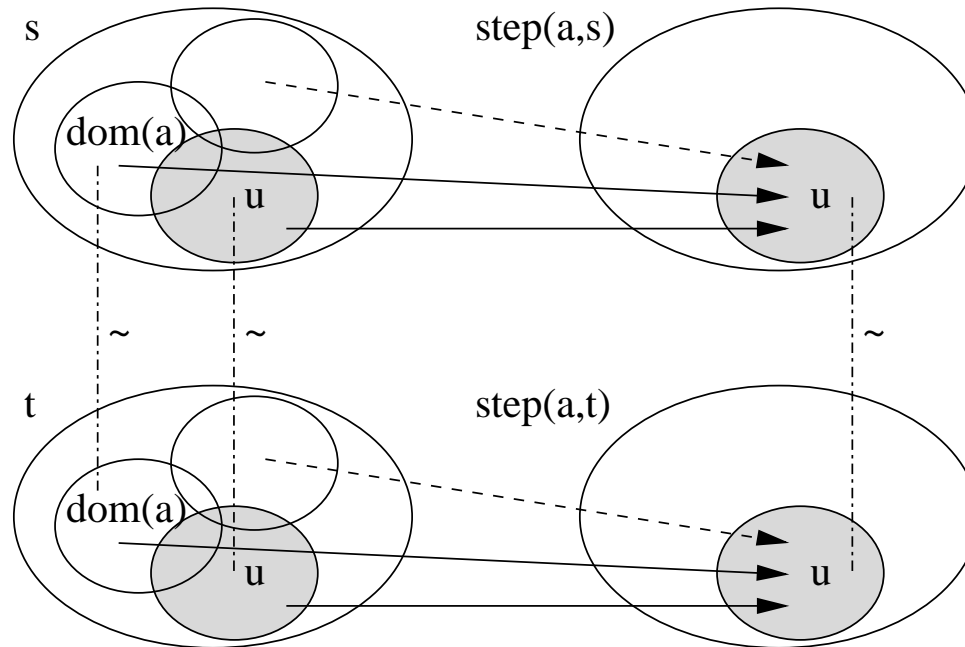
(local respect): else $step(a, s) \stackrel{sources(\alpha', u)}{\approx} t$, then

ind. hypothesis implies $run(\alpha', step(a, s)) \stackrel{u}{\approx} run(ipurge(u, a \frown \alpha'), t)$

Step consistency and respect

weakly_step_consistent \equiv

$$\forall a u s t. \text{dom}(a) \rightsquigarrow u \wedge s \overset{\text{dom}(a)}{\sim} t \wedge s \overset{u}{\sim} t \longrightarrow \text{step}(a, s) \overset{u}{\sim} \text{step}(a, t)$$



$$\text{step_respect} \equiv \forall a u s t. \text{dom}(a) \not\rightsquigarrow u \wedge s \overset{u}{\sim} t \longrightarrow \text{step}(a, s) \overset{u}{\sim} \text{step}(a, t)$$

$$\text{local_respect_left} \equiv \forall a u s t. \text{dom}(a) \not\rightsquigarrow u \wedge s \overset{u}{\sim} t \longrightarrow \text{step}(a, s) \overset{u}{\sim} t$$

$$\text{local_respect_right} \equiv \forall a u s t. \text{dom}(a) \not\rightsquigarrow u \wedge s \overset{u}{\sim} t \longrightarrow s \overset{u}{\sim} \text{step}(a, t)$$

Nondeterminism

$Step : action \rightarrow \wp(state \times state)$ new: non-unique outcome,
 $Run : action^* \rightarrow \wp(state \times state)$ partiality/reachability

$Noninterference \equiv \forall \alpha u \beta. ipurge(u, \alpha) = ipurge(u, \beta) \longrightarrow$
 $\forall s. (s_0, s) \in Run(\alpha) \longrightarrow \exists t. (s_0, t) \in Run(\beta) \wedge obs(u, s) = obs(u, t)$

Complications for weak step consistency \Rightarrow
stronger notions preserving **simultaneous** unwinding relation \approx :
uniform step consistency, step respect, and (right-hand) local respect

Requires in general **more proof effort**, yet not for two important cases:

- functional $Step(a)$
- two-level domain hierarchy $\{H, L\}$

Improvements over [Rus92]

- **weak** step consistency suffices also for transitive policies
- improvements on **access control interpretation**:
 - transitivity of policy **not required**
 - observable locations **need not** form a hierarchy
 - **stronger preconditions** of 2nd reference monitor assumption
- no restrictions on **unwinding relation**
- extension to **nondeterminism**

Nonleakage and Noninfluence

Event-based systems:

- visibility of **actions/events** is primary,
- secret state is secondary (via side-effects)

⇒ Noninterference

State-oriented systems:

- **secret state** is primary,
- actions/events are secondary or irrelevant

⇒ Nonleakage

State-event-systems:

- visibility of **actions/events** is relevant
- also **secrecy in state** is essential

⇒ Noninfluence

Concept

Language-based security: no assignments of **high**-values to low-variables, enforced by type system

Semantically: take (x, y) as elements of the **state space** with high-level data (**on left**) and low-level data (on right).

Step function $S(x, y) = (S_H(x, y), S_L(x, y))$

does not leak information from high to low

if $S_L(x_1, y) = S_L(x_2, y)$ (functional **independence**).

Observational equivalence $(x, y) \stackrel{L}{\sim} (x', y') \iff y = y'$ allows re-formulation:

$$s \stackrel{L}{\sim} t \longrightarrow S(s) \stackrel{L}{\sim} S(t) \quad (\text{preservation of } \stackrel{L}{\sim}) \\ \text{step consistency + respect}$$

Generalization to action sequences α and arbitrary policies \rightsquigarrow

Definition

$$\text{nonleakage} \equiv \forall \alpha s u t. s \stackrel{\text{sources}(\alpha, u)}{\approx} t \longrightarrow s \triangleleft \alpha \stackrel{u}{\simeq} t \triangleleft \alpha$$

“the **outcome** of u 's observation is **independent** of those domains from which no (direct or indirect) information flow is allowed.”

- like **Main Lemma**, but **no purging** (visibility of actions irrelevant)
- unwinding relation \sim is part of the notion:
the secrets for u are those state components not constrained by \sim
- corresponding unwinding theorem: nonleakage implied by
 $\text{weakly_step_consistent} \wedge \text{step_respect} \wedge \text{output_consistent}$

Variants

If (domains of) **actions** are **irrelevant**:

$$weak_nonleakage \equiv \forall \alpha s u t. s \stackrel{chain(\alpha, u)}{\approx} t \longrightarrow s \triangleleft \alpha \stackrel{u}{\simeq} t \triangleleft \alpha$$

where $chain : action^* \times domain \rightarrow \wp(domain)$

e.g., $v \in chain(a_1 \frown a_2 \frown a_3 \frown a_4, u)$ if $\exists v'. v \rightsquigarrow v' \rightsquigarrow u$

● implied by $output_consistent \wedge weak_step_consistent_respect$

Weak combination of step consistency and step respect:

$$\forall s u t. s \stackrel{\{w. w \rightsquigarrow u\}}{\approx} t \longrightarrow \forall a. step(a, s) \stackrel{u}{\simeq} step(a, t)$$

If additionally the **policy** is **transitive**:

$$trans_weak_nonleakage \equiv \forall s u t. s \stackrel{\{w. w \rightsquigarrow u\}}{\approx} t \longrightarrow \forall \alpha. s \triangleleft \alpha \stackrel{u}{\simeq} t \triangleleft \alpha$$

● implied by $weak_step_consistent_respect \wedge output_consistent$

Infineon SLE66 Case Study

Security objective: secret functionality and data is not leaked

Applied notion: nondeterministic transitive weak Nonleakage

Unwinding: equality on: non-secrets, phase, function availability

Minor complication: invariants required (\Rightarrow reachable states)

Results:

- underspecified functions require nonleakage assumptions
- anticipated (non-critical) single data leakage confirmed
- availability of secret functions is leaked
 \rightsquigarrow security objectives clarified: availability is public
- no other information leaked

Noninfluence

combining **noninterference** and **nonleakage**:

$$\text{noninfluence} \equiv \forall \alpha \ s \ u \ t. \ s \stackrel{\text{sources}(\alpha, u)}{\approx} t \longrightarrow s \triangleleft \alpha \stackrel{u}{\approx} t \triangleleft \text{ipurge}(\alpha, u)$$

- useful if both ...
 - certain **actions** should be kept **secret** and
 - initially present secret **data** should **not leak**
- stronger than *noninterference*
- implied by
 $\text{weakly_step_consistent} \wedge \text{local_respect} \wedge \text{output_consistent}$
- appeared already as **Main Lemma** (Rushby's Lemma 5)

Insights on observations and unwinding

- for given α , observational equivalence
 $s \triangleleft \alpha \stackrel{u}{\simeq} t \triangleleft \alpha \equiv \text{obs}(u, \text{run}(\alpha, s)) = \text{obs}(u, \text{run}(\alpha, t))$
as **equal outcome of tests** on s and t by u executing α
- observational preorder $s \triangleleft \alpha \stackrel{u}{\preceq} t \triangleleft \alpha \equiv \forall s'. (s, s') \in \text{Run}(\alpha) \longrightarrow \exists t'. (t, t') \in \text{Run}(\alpha) \wedge \text{obs}(u, s') = \text{obs}(u, t')$
also entails **preservation of enabledness** of α
- observation may be encoded by enabledness of “probing” actions
 \Rightarrow **observational preorder** \simeq **enabledness relation** [Mantel-PhD03]
- observational equivalence/preorder induced by obs ...
 - is reflexive and transitive
 - is implied by unwinding (which maybe is not an equivalence)
 - can be regarded as **reflexive+transitive closure** of unwinding
 - often **coincides** with unwinding relation

Conclusion

- refinements and generalizations on Rushby's work
- introduction of new notions for data flow security: noninterference + nonleakage = noninfluence
- insights on unwinding and observation relations
- application in machine-assisted security analysis:
 - smart card processors (secrecy)
 - operating systems (process separation)